

# Advanced Algorithmics

*Strategies for Tackling Hard Problems*

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## *Lecture 20*

2017-06-29

## 5.7 Dual LPs & The Primal-Dual Schema

Starting with an original ("primal") LP, how can we bound on its optimal objective value?

↳ upper bound → find feasible solution  
lower bound → ?

$$\min \quad 7x_1 + x_2 + 5x_3$$

$$\text{s. t.} \quad y_1 \cdot (x_1 - x_2 + 3x_3) \geq 10 \quad y_1$$

$$y_2 \cdot (5x_1 + 2x_2 - x_3) \geq 6 \quad y_2$$

$$x_1, x_2, x_3 \geq 0$$

$$7x_1 + x_2 + 5x_3 \geq x_1 - x_2 + 3x_3 \geq \underline{10}$$

$$7x_1 + x_2 + 5x_3 \geq \underbrace{x_1 + 2x_2}_{\neq}$$

$$7x_1 + x_2 + 5x_3 \geq 6x_1 + x_2 + 2x_3 \geq \underline{16}$$

$$\begin{aligned} 7x_1 + x_2 + 5x_3 &\geq \underbrace{y_1}_{!} (x_1 - x_2 + 3x_3) \\ &\quad + \underbrace{y_2}_{!} (5x_1 + 2x_2 - x_3) \\ &\geq 10y_1 + 6y_2 \end{aligned}$$

Dual:

$$\max \quad 10y_1 + 6y_2$$

$$\text{s. t.} \quad y_1 + 5y_2 \leq 7$$

$$-y_1 + 2y_2 \leq 1$$

$$3y_1 - y_2 \leq 5$$

$$y_1, y_2 \geq 0$$

Optimal solution:

$$x^* = (1.75, 0, 2.75) \text{ with } c^T x^* = 26.$$

## Dual LPs

$$\begin{array}{ll} \min & c^T x \\ \text{s. t.} & Ax \geq \bar{b} \quad \textcircled{2} \\ & x \geq 0 \end{array} \quad c = (7, 1, 5)$$
$$\begin{array}{ll} \max & b^T y \\ \text{s. t.} & A^T y \leq c \quad \textcircled{3} \\ & y \geq 0 \end{array} \quad (A^T y)^T = y^T A \leq c^T$$
$$A = \begin{pmatrix} 1 & -1 & 3 \\ 5 & 2 & -1 \end{pmatrix} \quad b = \begin{pmatrix} 1 \\ 6 \end{pmatrix}$$

### Generalizations:

- ▶  $i$ th constraint in primal with  $\geq \iff y_i \geq 0$
- ▶  $i$ th constraint in primal with  $= \iff y_i$  unconstrained

### Lemma 5.29 (Weak Duality)

If  $x$  and  $y$  are feasible solutions for the primal resp. dual LP, it holds that  $\underline{c^T x} \geq \underline{b^T y}$  ◀

Proof:  $c^T x \geq y^T (Ax) \geq y^T b = b^T y$

↑  $x \geq 0$   $\textcircled{1}$                        $\textcircled{2}$

□.

# Duality Theory

Indeed one can show by a closer study that the optimal objective values *match*.

## Theorem 5.30 (Strong duality)

The primal LP has a finite optimal objective if and only if the dual has. If  $\underline{x}^*$  resp.  $\underline{y}^*$  are two optimal solutions to the primal resp. dual LP then  $\underbrace{c^T \cdot x^* = b^T \cdot y^*}$  holds. ◀

## Theorem 5.31 (Complementary Slackness Conditions (CSC))

Let  $x$  and  $y$  be feasible solutions to the primal and dual LP. // none infeasible

The pair  $(x, y)$  is optimal if and only if

1.  $x_j = 0$  or  $\sum_{1 \leq i \leq m} a_{i,j} \cdot y_i = c_j$  for all  $1 \leq j \leq n$ , and
2.  $y_i = 0$  or  $\sum_{1 \leq j \leq n} a_{i,j} \cdot x_j = b_i$  for all  $1 \leq i \leq m$ .

## Remark 5.32

1. Strong duality implies that the LP threshold decision problem is in  $\mathcal{NP} \cap \text{co-}\mathcal{NP}$ :  
Yes-certificate: feasible solution; No-certificate: feasible solution for the dual.
2. For ILPs, we only get weak duality.

## Set Cover LP and its dual

$$V(u) = \{j : u \in S_j\}$$

$$S = \{S_1, \dots, S_k\} \quad S_j \subseteq U$$

$$\min \sum_{j=1}^k c(S_j) \cdot x_j$$

$$\text{s. t. } \sum_{j \in V(u)} x_j \geq 1 \quad \forall u \in U$$

$$\underline{x \geq 0}$$



↑  
automatic  
by rules

$$\max \sum_{u \in U} y_u$$

$$\text{s. t. } \sum_{u \in S_j} y_u \leq c(S_j) \quad \forall j \in [k]$$

$$y \geq 0$$

### Intuition:

Pack as much ( $y_u$ ) of good  $u$  as possible, so that for group  $S_j$  its capacity  $c(S_j)$  is exceeded.

# Analysis of greedySetCover by dual fitting

```
1 procedure greedySetCover( $n, S, c$ )
2    $\mathcal{C} = \emptyset, C = \emptyset$ 
3   // For analysis  $j = 1$ 
4   while  $C \neq [n]$ 
5      $j^* = \arg \min_{i \in [n]} \frac{c(S_i)}{|S_i \setminus C|}$ 
6     Add  $j^*$  to  $\mathcal{C}$ 
7      $C = C \cup S_{j^*}$ 
8     // For analysis:  $\alpha_j = \frac{c(S_{j^*})}{|S_{j^*} \setminus C|}; j = j + 1$ 
9     // For analysis: for  $u \in S_{j^*} \setminus C$  set  $\underline{\text{price}}(u) = \alpha_j$ 
10  return  $\mathcal{C}$ 
```

price( $u$ ) is essentially a dual variable  $y_u$

BUT not directly dual-feasible

$$\sum_{u \in U} \text{price}(u) = c(\mathcal{C}) \rightarrow y \text{ was dual-feasible} \\ \Rightarrow \mathcal{C} \text{ was optimal}$$

## Lemma 5.33

$y_u = \text{price}(u)/H_n$  is dual-feasible. ◀

Proof:  $e_1, e_2, \dots, e_n$  in the order they are covered by greedy set cover

$|S_j| = \ell \rightarrow$  when  $e_i$  was covered,  $S_j$  contains  $\geq \ell - (i-1)$  uncovered elem.

$\Rightarrow S_j$  could cover  $e_i$  (assuming  $e_i \in S_j$ ) with per elem cost  $\leq \frac{c(S_j)}{\ell - i + 1}$

$\hookrightarrow$  also. chooses most cost-effective set  $S_{j^*} \rightarrow \alpha_j \leq \frac{c(S_j)}{\ell - i + 1}$

$$y_{e_i} \leq \frac{1}{H_n} \cdot \frac{c(S_j)}{e^{-i+1}}$$

Consider constraint for  $S_j$

$$\sum_{u \in S_j} y_u = \sum_{m=1}^e y_{e_{im}} \leq \frac{c(S_j)}{H_n} \left( \frac{1}{1} + \frac{1}{2} + \dots + \frac{1}{e} \right)$$

$$= \frac{He}{H_n} \cdot c(S_j) \leq c(S_j) \quad \text{for } e \leq n \quad \leadsto \text{dual constraint} \checkmark$$

□

↳ Can easily  $H_n$ -approx. :

$$c(\mathcal{U}) = \sum_{u \in \mathcal{U}} \text{price}(u) = H_n \underbrace{\sum_{u \in \mathcal{U}} y_u}_{\text{dual objective}} \stackrel{\text{weak duality}}{\leq} H_n \cdot \text{OPT}_{\text{frac}} \leq H_n \cdot \text{OPT}$$

## Integrality Gap of Set Cover

← for minimization problem

Previous result shows that integrality gap  $\frac{OPT}{OPT_{frac}} \leq H_n$ .

Can we give a lower bound?

### Theorem 5.34 (Integrality Gap of Set Cover)

For the set cover ILP and its relaxation holds

$$H_n \sim \ln(n)$$

$$\underbrace{\frac{OPT}{OPT_{frac}} \geq \frac{\log_2(n+1)}{2^{\frac{n}{n+1}}}}_{\text{show below}} \sim \frac{1}{2 \ln 2} H_n \approx 0.721 H_n$$

⇒ essentially not possible to improve greedy algorithm by any LP relaxation-based method

Proof:  $n = 2^l - 1$   $l \in \mathbb{N}$   $\rightarrow U = \{1, \dots, n\} \cong$   $l$ -bit binary numbers

view  $i \in U$  as a vector  $\vec{i} \in \{0, 1\}^l$  using  $(i \bmod n)_2$  (and set  $\vec{n} = \vec{0}$ )

$$S_j = \{i : \vec{i}^T \vec{j} = 1 \pmod{2}\}$$

$$j \in [n]$$

$$c(S_j) = 1 \quad \uparrow \quad \mathbb{Z}_2$$

$$\begin{array}{ccc|c} 0 & 1 & 0 & 2 \\ 1 & 1 & 1 & 7 \\ \hline 0 & 1 & 0 & = 1 \end{array} \quad \vec{2}^T \vec{7} = 1$$



Can check  $|S_j| = \frac{n+1}{2}$   $|V(i)| = \frac{n+1}{2}$

each value  $i$  contained in  $\frac{n+1}{2}$  sets

$\Rightarrow$  ①  $x_j = \frac{2}{n+1} \Rightarrow$  fractional set cover

with  $OPT_{frac} = n \cdot \frac{2}{n+1}$

② We need  $\ell$  sets to cover  $U$

$p < \ell$ , sets  $S_{i_1}, \dots, S_{i_p}$

$$A = \begin{pmatrix} - & \vec{i_1} & - \\ & \vdots & \\ - & \vec{i_p} & - \end{pmatrix}$$

$p \times \ell$  matrix

$\Rightarrow$  rank  $\leq p < \ell$

$\Rightarrow$  null space  $(A) \neq \{0\}$

$\Rightarrow \exists j : A \cdot \vec{j} = \vec{0}$

$\Rightarrow j \notin S_{i_1}, \dots, S_{i_p} \Rightarrow$  not a set cover  $\Rightarrow OPT \geq \ell = \log_2(n+1) \square$

# Primal-Dual Schema

So far:

- ▶ ad hoc methods, a posteriori justified by LP arguments
- ▶ rounding algorithms, must solve primal LP to optimality (expensive!)

Can we use duality more directly? Yes!

Idea: Start with two solutions; dual feasible, primal is infeasible, but integral (kindly). Update solutions to match more of CSC conditions

↳ all satisfied exactly  $\rightarrow$  optimal

for hard problems  not be possible efficiently

$\Rightarrow$  relax CSC's a bit, so that

- $x$  remains feasible & integral
- $y$  require relaxed form of CSC
  - ↳  $y$  only gives some lower bound

## CSC for set cover

Complementary Slackness Conditions for Set Cover

$$x_j = 0 \vee \sum_{u \in S_j} y_u = c(S_j) \quad \forall j \in [k] \quad (\text{CSC 1})$$

$\nwarrow$  can be relaxed

$$y_u = 0 \vee \sum_{j \in V(u)} x_j = 1 \quad \forall u \in U \quad (\text{CSC 2})$$

$\nwarrow$  important

Problem: In general only simultaneously fulfilled by fractional solutions

Relax dual <sup>CSCs</sup> constraints to

$$y_u = 0 \vee \sum_{j \in V(u)} x_j \leq f \quad \forall u \in U$$

i.e., every element at most  $f$  times  $\rightsquigarrow$  trivially fulfilled.

Ideas a) Increase  $y_u$  until (CSC 1) fulfilled for one set  $S_j$  with currently  $x_j = 0$   
 $\rightarrow x_j = 1$

b)  $c(S_j) - \sum_{u \in S_j} y_u$  minimal (but not 0)

# Primal Dual Set Cover

```
1 procedure primalDualSetCover( $n, S, c$ )
2    $f =$  global frequency
3    $\vec{x} = \vec{0}, \vec{y} = \vec{0}, T = [n]$ 
4   while  $T \neq \emptyset$ 
5     Choose  $u \in T$  arbitrary  $\checkmark$  compute  $\delta = \min_{j: x_j=0} c(S_j) - \sum_{u \in S_j} y_u$ 
6     Increase  $y_u$  until CSC holds for (at least) one more set  $S_j$ 
7     for all  $S_j$  with  $\sum_{u \in S_j} y_u = c(S_j)$ 
8        $\mathcal{T} = \mathcal{T} \setminus S_j$ 
9        $x_j = 1$ 
10  return  $\{j \in [k] : x_j = 1\}$ 
```

## Theorem 5.35

primalDualSetCover is an  $f$ -approximation for SET-COVER. ◀

Proof:  $\mathcal{C} = \{j \in [k] : x_j = 1\}$  is a set cover  $\checkmark \rightarrow x$  feasible

Additionally for  $j$  with  $x_j = 1$  holds  $\sum_{u \in S_j} y_u = c(S_j)$  (CSC1)

holds when  $x_j$  was set to 1, all  $y_u$  with  $u \in S_j$  never touched again

$$\sum_{j=1}^k c(S_j) \cdot x_j \stackrel{(cscd)}{=} \sum_{j=1}^k x_j \sum_{u \in S_j} \gamma_u$$

//

$$c(\emptyset) = \sum_{u \in U} \gamma_u - \underbrace{\sum_{j \in V(u)} x_j}_{\leq f} \quad |V(u)| \leq f$$

$$\leq f \underbrace{\sum_{u \in U} \gamma_u}_{\text{dual objective}}$$

$$\stackrel{\substack{y \text{ feasible} \\ \text{weak duality}}}{\leq} f \cdot \text{OPT}_{\text{frac}}$$

$$\leq f \cdot \text{OPT}$$

□

## 5.8 Arbitrarily Good Approximations

Goal: Prove some problems inapproximable  $\rightarrow$  need to define what approximability means

### Definition 5.36

Let  $U = (\Sigma_I, \Sigma_O, L, L_I, M, cost, goal)$  an optimization problem.

An algorithm  $A$  is called *polynomial time approximation scheme (PTAS)* for  $U$ , if  $A$  computes for each pair  $(x, \varepsilon) \in L_I \times \mathbb{R}^+$  a feasible solution which is at most a factor  $(1 + \varepsilon)$  worse than the optimum (i.e.,  $\varepsilon$  is the relative error) and needs a polynomial time in  $|x|$  (i.e.,  $\mathcal{O}(|x|^{exp(1/\varepsilon)})$  is possible).  $\Rightarrow$  approximable to any desired error.

If the running time of  $A$  is polynomially bounded in  $|x|$  and  $\varepsilon^{-1}$ ,  $A$  is called a *fully polynomial time approximation scheme (FPTAS)* for  $U$ . ◀

In practice, we would like to have FPTAS

**Definition 5.37**  $\exists c : \exists c\text{-approx. poly-time}$

APX =  $\{U \in \text{NPO} \mid \exists \text{polynomial time } c\text{-approximation algorithm for } U, c \text{ constant}\}$ . ◀

Vertex-Cover  $\in$  APX

Set-Cover maybe not APX